

Parts Certificate GB-1659

Issued by	NMO	
In accordance with	The applicable requirements of Welmec Guides 7.2 and 8.8, and OIML R117-1 Edition 2007 (E).	
Applicant	Heinrichs Messtechnik GmbH Robert-Perthel-Strasse 9 50739 Cologne Germany	
In respect of	A family of Coriolis mass-flow meters tested as a separate part of a liquids other than water instrument.	
	Manufacturer: Heinrichs Messtechnik GmbH Type: TMU-S### sensor with a UMC3 transmitter	
Characteristics	Suitable for a liquids other than water instrument with the following characteristics:	
	Minimum rate of flow:600 kg/hrMaximum rate of flow:700,000 kg/hrAccuracy class:0.5Environment classes:M2 / E2Ambient temperature range:-40 °C to +55 °C (TMU sensor)-20 °C to +55 °C (UMC3 transmitter)Humidity:Open, Condensing	
Description and documentation	The device is described in the Descriptive Annex. Documents appertaining to this Evaluation certificate are held by NMO.	
Remarks	The conformity was established by testing and examinations described in the associated Evaluation Report P02148.	

Issue Date: 06 March 2019

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G Stones Technical Manager For and on behalf of the Head of Technical Services

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Descriptive Annex

1 INTRODUCTION

The TMU family of Coriolis Flow Sensors, together with its associated UMC3 transmitter, are designed for the direct mass-flow measurement of gases and liquids in piping systems irrespective of their conductivity, density, temperature, pressure or viscosity.

The TMU sensor is available in sizes, ranging from Qmin = 600 kg/hr to Qmax = 700,000 kg/hr. The sensor and transmitter are connected by a special 10 cored cable and may be installed at distances of up to 200 m apart.

The UMC3 transmitter possesses two microprocessor units one for controlling the process sequence and communications and one for controlling the BE2 control unit, as well as a high-speed DSP (Digital Signal Processor) for controlling the demanding measuring tasks.

With the UMC3 transmitters BE2 control unit, which possesses an LCD display and 6 control keys, the meter can be programmed by the operator with the required parameters and desired features. The control unit microprocessor possesses its own independent program for controlling the control unit and communicates its activity directly to the main microprocessor.

Once programmed and sealed, a glass windowed lid allows for visual observation of the measurements.

2 DESCRIPTION

2.1 The TMU Mass-flow Sensor

The mass-flow sensor consists of the following components:

- A main body, which is designed with a minimum Ingress protection of IP65 to protect the internal components from damage or contamination.
- An inlet and outlet flange for connection to a piping system allowing the medium to be measured to flow in and out of the sensor where it is split into the two parallel arranged tubes for analysis.
- Two parallel arranged measuring tubes which are set into oscillation for determining the mass-flow through the sensor.
- An exciter coil powered by the associated transmitter to set and hold the measuring tubes in oscillation.
- Two pick-up coils used to capture the mass-flow proportional phase shift between the inlet and the outlet legs of the measuring tubes.
- A temperature sensor connected to one of the measuring tubes used for temperature related compensation of the sensor and medium.
- A terminal box allowing for the connection of the cable from the associated transmitter.

2.2 The UMC3 Transmitter

The mass-flow transmitter consists of the following components:

- An aluminium enclosure with two compartments.
- An electronic compartment with intrinsically safe electronics for the measurement, assessment and communication of the measured vales.

- A control unit with push buttons and a display for programming the parameters and features of the meter, and for visually monitoring the results.
- A terminal compartment for the connection of the cable to the sensor, the power supply and the communication outputs.

2.3 Operating principle

The transmitter's exciter circuit sets the measuring tubes into a vibrating back and forth motion around the flange's rotational axis. The frequency of this resonant motion is determined by the sensor's construction and by the density of the medium. The time difference between the two pick-up coil signals is directly proportional to the mass flowing through the tubes. This time difference and the frequency of resonance are measured to determine the mass-flow and density respectively. From these two values the volume flow can be determined.

The captured mass-flow value is transmitted by the transmitter via either a pulse output which may be parametrised as required, or a current output. When transmitted via pulse, a second pulse signal is also available for determining the direction of flow. This is achieved by shifting the rising edge of the pulse 90° in front or 90° behind the mass-flow pulse.

The measured density value may be transmitted using the 4 - 20 mA current output. MODBUS or HART communication interfaces are also available for communicating numerous parameters simultaneously, or for requesting information of the meter's status. The sensor can be used bi-directionally with consistent accuracy.

2.4 Available Devices

2.4.1 The UMC3 Transmitter

The transmitter is available with the two power supply versions:

- 24 VDC
- 230 VAC

2.4.2 The TMU Sensor –

The sensor is presently available in 8 sizes with numerous process connections. The available sensor sizes and their measurement ranges are as follows:

TMU-S015	-	600 kg/hr to 9,000 kg/hr
TMU-S025	-	1,500 kg/hr to 30,000 kg/hr
TMU-S040	-	3,000 kg/hr to 60,000 kg/hr
TMU-S050	-	4,000 kg/hr to 80,000 kg/hr
TMU-S080	-	6,000 kg/hr to 120,000 kg/hr
TMU-S100	-	10,000 kg/hr to 200,000 kg/hr
TMU-S150	-	23,500 kg/hr to 460,000 kg/hr
TMU-S200	-	35,000 kg/hr to 700,000 kg/hr

2.4.2.1 Pressure Correction

Depending on the TMU Sensor characteristics, a dynamic pressure correction by means of MID compliant pressure transmitter is required when the pressure variation in the final application has an effect of more than ¹/₅ of the Maximum Permissible Error (MPE) for that application.

3 TECHNICAL DATA

Measurand: The meter's primary application is the measurement of mass-flow of liquids other than water. Units of measurement can be set; however, they must be set before the custody transfer stamp is set. After setting, a change of the unit is not possible. The indication of the measurand can be performed in, for mass: gr/hr, kg/hr, Tonne/hr, or volume such as: l/hr, m³/hr.

Liquid types: The types of liquids covered by this part of the directive are for example; oils, oil by-products, chemicals, potable liquids. for applications such as; Fuel dispensers for motor vehicles, and loading and unloading of ship, rail and road tankers, ship-fuel bunkering.

3.1 Rated operating conditions ranges

Ambient temperature range:

Temperature:

TMU sensor:	-40 °C to +55 °C.
UMC3 transmitter:	-20 °C to +55 °C

(The LCD display of the UMC3 transmitter limits its ambient temperature range to -20°C)

Liquid temperature range: TMU Sensor:	-40°C to +260 °C
Operating pressure (depen Min. Max.	dant on sensor size, see table 1): 0.5 bar 175 bar
Density Range: Min. Max.	300 kg/m³ 2000 kg/m³
Viscosity range: Max.	2,000 mPa
Ingress Protection: Transmitter: TMU Sensor: The meters may be used inde	Min. IP65 Min. IP65 oors or outdoors.
Environmental Classes: Electromagnetic Class: Humidity Class: Mechanical Class:	E2 Open, Condensing M2
Accuracy class of meters: Mass-flow, all sensor sizes: Density, all sensor sizes: Volume, all sensor sizes:	0.5 0.5 0.5

0.5

In table 1 the measuring ranges of the devices covered are stated for each sensor together with the minimum measured quantities (MMQ).

Sensor	MMQ [kg]	Qmin [kg/hr]	Qmax [kg/hr]	Max. pressure [bar]
TMU-S015	21	586	9286	175
TMU-S025	50	1500	30000	152
TMU-S040	103	3001	61044	95
TMU-S050	140	4000	80000	80
TMU-S080	202	5825	122240	80
TMU-S100	350	10000	200000	50
TMU-S150	750	22759	460659	70
TMU-S200	1200	35000	700000	60

Table 1: Flow ranges and process pressures of the sensors

Where volumes are to be measured, the applicable values for Qmax, Qmin and MMQ are defined by the following equation:

Qmin volume = Qmin mass / minimum product density Qmax volume = Qmax mass / maximum product density MMQ volume = MMQ mass / minimum product density

Where minimum and maximum product density represents the minimum and maximum expected densities of the product to be measured.

3.2 Technical documentation

The Technical File is held at NMO.

3.3 Software

UMC3 contains two processors each with their own software, the main processor and the control unit processor, only the software of the main processor has legal metrology relevance.

The classified software of the main processor with legal metrology relevance carries the following version number and check sum which is shown during the start-up sequence when powered on:

Software version number:	3.25
Check sum:	8DCB

Non-legally relevant software relates only to the BE2 control unit

BE2 software version number: 2.132

Once the "Custody Transfer Stamp" has been set, no amendments to settings or software parameters are possible.

The software of the UMC3 is classified in accordance to the WELMEC Guide 7.2 (2018) as a "Type P software without extension".

4 PERIPHERAL DEVICES AND INTERFACES

4.1 Interfaces

The meter has the following interfaces, some of which are standard installations others optional, only installed upon request. The meter may have any combination of the following interfaces:

- Pulse outputs B1 and B2
- Status output B3
- Current output (4 20 / 21.6) mA
- HART Communication (optional)
- Modbus RTU (optional)
- Binary input (Custody push-button)

The transmitter has the following metrological means of communication:

- Pulse, Frequency
- 4 20mA current output and Modbus RTU.

4.2 Peripheral devices

The instrument may be connected to any peripheral device that has been issued with Parts Certificate by a Notified Body responsible for Module B under Directive 2014/32/EU and bears the CE marking of conformity to the relevant directives; or

A peripheral device without a Parts certificate may be connected under the following conditions:

- it bears the CE marking for conformity to the EMC Directive;
- it is not capable of transmitting any data or instruction into the measuring instrument, other than to release a printout, checking for correct data transmission or validation;
- it prints measurement results and other data as received from the measuring instrument without any modification or further processing; and
- it complies with the applicable requirements of Paragraph 8.1 of Annex I.

5 APPROVAL CONDITIONS

The certificate is issued subject to the following conditions:

5.1 Inscriptions

The instrument shall bear the following inscriptions:

- Manufacturer's name, registered trade name or registered trade mark and postal address
- Parts Certificate number
- Designation or Type
- Serial Number
- Year of Manufacture

6 LOCATION OF SEALS AND VERIFICATION MARKS

6.1 Data Plate

The data plate is located on the instrument, and is secured, either by sealing or by being of a form such that it is destroyed when removed.

6.2 The sealings must bear an official mark, which may be either:

- a mark of the manufacturer and/or manufacturer's representative, or
- an official mark of a verification officer.

6.3 Custody Transfer Stamp

The state of the "Custody Transfer Stamp" is requested from the software via an input pin of the microcontroller. Is the stamp state active, settings via the control unit, Modbus- or the HART® interface can no longer be initiated. Upon completion of all assessments, the "Custody Transfer Stamp" is set by applying the bridge EICHB. on the top electronic staple from position 1 - 2 to position 2 3. In custody transfer mode, merely self-test and system errors can be annulled by means of an external push button switch (Custody transfer button).

6.4 Transmitter

After the software stamp has been set, the lids of the transmitter are screwed onto the main enclosure. Both lids are sealed with the main body using adhesive security seal. The sticker label covers the sensors rating plate. An additional verification sticker may be adhered to the window lid of the enclosure.

6.5 The Sensor

6.5.1 Terminal box

The lid of the sensors terminal box is screwed into position and sealed applying an adhesive security seal across the lid and the terminal boxes main body.

6.5.2 Service lid

Where larger sensors are available with removable sensor lids for servicing purposes, two security seals with the minimum dimensions of 60 mm x 20 mm shall be used. The seals are attached on adjacent sides of the sensor (e.g. top and bottom or left and right side).

If the service lid is secured or welded to the main body, this security seal can be omitted.

7 ALTERNATIVES

There are currently no alternatives.

8 ILLUSTRATIONS

- Figure 1 Example of Rating Plates
- Figure 2 UMC3 mounted on a wall bracket
- Figure 3 TMU-S015 /TMU-S025 sensor with connected cable in fully welded body
- Figure 4 TMU-S040 in a square welded and silicon sealed construction
- Figure 5 Schematic installation guide of the flow-meter
- Figure 6 Sealing Measures
- Figure 7 Version and Checksum

CERTIFICATE HISTORY

ISSUE NO.	DATE	DESCRIPTION
GB- 1659	06 March 2019	Evaluation certificate first issued.
-	-	No revisions have been issued.

FA-11-0-H Custody transfer parts certificate number: xxxxx m B1 See Manual
TMU-S100-335B-A00-FA-11-0-H 987654 Custody tra 987654 Custody tra 987654 Custody tra 01ML R117 parts certifi 2019/01 number: xx 1.4571/1.4404 number: xx 40°C to 100°C 40°C to 100°C 40°C to 455°C 0 bar 0 bar 0 bar 20000 kg/h See Ma rtC: -20356,9 See Ma M20 x 1.5 15
00::: 00:: 10:: 10:: 10:: 10:: 11: 11
Heinrichs KOBOLD Group D-50739 Köln Sobert-Perthel-Str. 9 Novw.heinrichs.eu MT 01 ATEX E 149) I 1/2 G Ex ia IIC T6-T2 Ga/G

Figure 1

Example of Rating Plates

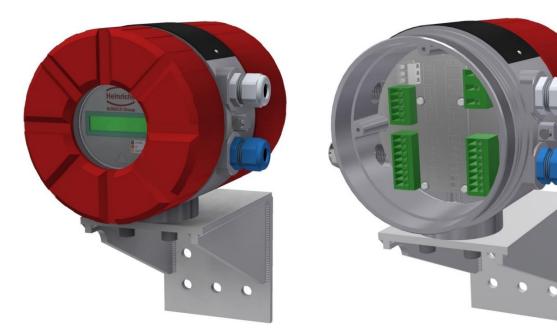


Figure 2

UMC3 mounted on a wall bracket



Figure 3

TMU-S015 /TMU-SO25 sensor with connected cable in fully welded body



TMU-S040 in a square welded construction



Figure 4 TMU- S040 with silicon sealed construction

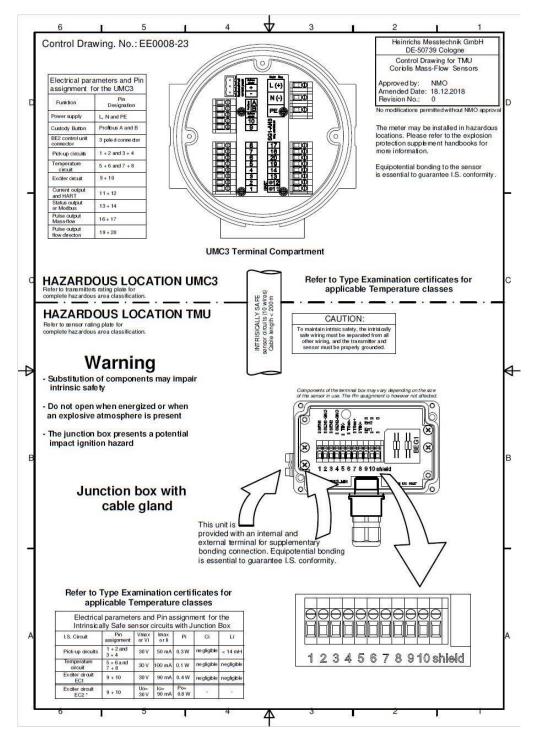


Figure 5 Schematic installation guide of the flow-meter.



Image 1: Seals on the transmitter covering the lid and rating plate



Image 2: Seal securing the sensors terminal box lid

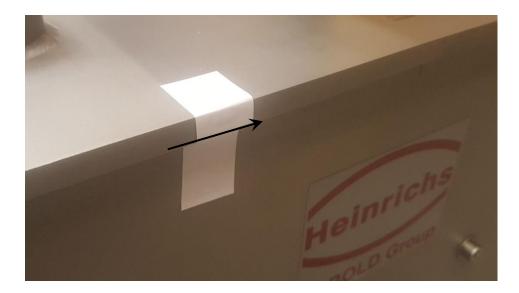




Image 3 and 4: Seal securing the sensors removable lid

Figure 6 Sealing Measures



Figure 7 Version and Checksum

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